File System Block-Mapping under Linux

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The Linux kernel includes a powerful, filesystem independant mechanism for mapping logical files onto the sectors they occupy on disk. While this interface is nominally available to allow the kernel to efficiently retrieve disk pages for open files or running programs, an obscure user-space interface does exist. This is an interface which can be handily subverted (with bmap and freinds) to perform a variety of functions interesting to the computer forensics community, the computer security community, and the high-performance computing community.

1 Downloading

bmap is publicly available at the following location

- Web page: http://www.scyld.com/software/bmap.html
- Source: ftp://ftp.scyld.com/pub/bmap/bmap-1.0.17.tar.gz

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2 Usage

The bmap package consists of 2 tools and a development library. The standalone tools bmap and slacker are provided as both useful standalone utilities and reference implementations of libbmap applications.

2.1 Building bmap

make and make install should take care of it.

At this time, we have only worked out a bmap implementation on Linux.

These tools will install under /usr/local by default.

2.2 Invoking the tools

2.2.1 bmap invocation

bmap [<0PTIONS>] [<target-filename>]

```
Where OPTIONS may include any of:
```

```
-doc VALUE
     where VALUE is one of:
     version
          display version and exit
     help
          display options and exit
     man
          generate man page and exit
     sgml
          generate SGML invocation info
-mode VALUE
     where VALUE is one of:
     map
          list sector numbers
     carve
          extract a copy from the raw device
     slack
          display data in slack space
     putslack
          place data into slack
     wipeslack
          wipe slack
     checkslack
          test for slack (returns 0 if file has slack)
     slackbytes
          print number of slack bytes available
     wipe
          wipe the file from the raw device
     frag
          display fragmentation information for the file
     checkfrag
          test for fragmentation (returns 0 if file is fragmented)
-outfile <filename>
     write output to ...
-label
     useless bogus option
-name
     useless bogus option
```

```
-verbose
     be verbose
-log\text{-thresh} < \! none \mid fatal \mid error \mid info \mid branch \mid progress \mid entryexit >
     logging threshold ...
-target <filename>
     operate on ...
2.2.2 slacker invocation
slacker [<0PTIONS>] [<path-filename>]
Where OPTIONS may include any of:
-doc VALUE
     where VALUE is one of:
     version
          display version and exit
     help
          display options and exit
     man
          display man and exit
     sgml
          generate SGML invokation info
-mode VALUE
     where VALUE is one of:
     capacity
          measure slack capacity of path
     fill
          fill slack space with user data
     frob
          fill slack space with random data
     pour
          write out the contents of slack space
     wipe
          clear the contents of slack space
-outfile <filename>
     write output to ...
-verbose
     be verbose
-log-thresh < none | fatal | error | info | branch | progress | entryexit>
```

logging threshold ...

2.3 Limitations

The bmap works against filesystems mounted on block devices. You will not to be able to operate against filesystems mounted via Samba, NFS, or any other network filesystem.

If you simply cannot use bmap on the machine storing the block device or block device image, you can try the linux network block driver to export the block device to the machine from which you wish to bmap. Also, Scyld's userfs user-level filesystem code includes a sample application, bush, which is linked against bmap.

2.4 Technical Description / Implementation

2.4.1 VFS – Linux 'Virtual Filesystem Switch'

These notes are based on Linux 2.2.5 but should be widely portable to other versions of the Linux kernel. compiled with

```
#include <linux/fs.h>
lives at

((struct inode_operations *)foo)->bmap

and is prototyped as

int foo_bmap(struct inode *inode,int block);

2.4.2 FIBMAP - userspace interface via ioctl

#include <sys/ioctl.h>
#include <linux/fs.h>

retval=ioctl(fd,FIBMAP,&block_pos);
```

Where block_pos passes the index of the block you wish to map and returns the index of that block with respect to the underlying block device. It is important to understand exactly what these arguments expect and what they return:

blocksize

stat() is is happy to provide callers with a blocksize value. This blocksize is often not the right one for use with bmap. The stat() man page indicates that stat.st_blksize is for efficient filesystem I/O. The blocksize suited for use with bmap is available via ioctl: ioctl(fd,FIGETBSZ,&block_size) when performed against a file descriptor returns the file block size in bytes.

index of the block you wish to map

index is computed in units of blocksize per the above discussion. index is zero-based.

offset of that block with respect to the underlying block device

index is computed in units of blocksize per the above discussion. index is zero-based. **NOTE:** This offset is against the start of the block device on which the filesystem is mounted. This is usually a partition – not the physical device on which the partition sits. Files with holes usually return 0 as their block offset for blocks that exist in the hole.

2.4.3 Device Determination;

bmap and slacker contain code that allows them to do I/O against the raw block device. Under linux, it takes a bit of work just to determine **where** a file is located. stat() returns the major/minor of the block device via stat.st_dev - but this is difficult information to use.

Three ways leap immediately to mind:

mknod

A new device node could be created somewhere with the major/minor numbers supplied by stat(). A serious downside is that a writeable volume must exist on the system in order for the device nodes to be created.

walk /dev

This method can be done with an existing filesystem, but the cost can be high. A /dev tree may feature thousands of entries on a modern system and the target entry may be buried hundreds or thousands of entries deep. This penalty could be extreme if the /dev tree were located on a remote system – although this situation should be extremely rare.

maintain an internal mapping

This method is an attempt to speed up lookups in /dev by build-time precomputing a table with major/minor and node names for many block devices. The target device is checked to determine that the major/minor numbers are actually correct as a check.

bmap and freinds maintain an internal mapping for fast lookups. This saves measureable time when bmap is invoked as the object of a file-system walk over tens of thousands of files. Currently, however, they do not search or store this mapping very efficiently.

2.5 Advanced Block Map Techniques

2.5.1 Undeleting files (brute force)

- 1. Determine byte offset of string with respect to beginning of block device containing filesystem
- 2. Compute sector(s) containing string
- 3. Generate inode sector lists exhaustively over the filesystem

```
find * -exec bmap {} >> /another_file_system/blocks \;
```

4. Sort lists from step (3) into a single list

```
cat /another_file_system/blocks | sort -n | uniq > > /another_file_system/blocks.sorted
```

- 5. Identify the contiguous set of unallocated sectors surrounding the sectors from step (4)
- 6. Extract the sector set identified in step (5)
- 7. Done

2.5.2 Undeleting files (openinode)

Scyld's openinode kernel patch relieves most of the complexity of 'undeleting' files. However, a simple postprocessing step is often useful when attempting to validate recovered files – a check should be made to determine if file blocks from the recovered file have been subsequently allocated to other files.

- 1. Generate inode sector list for the recovered file
- 2. Generate inode sector lists exhaustively over the filesystem

```
find * -exec bmap {} >> /another_file_system/blocks \;
```

3. Sort lists from step (3) into a single list

```
cat /another_file_system/blocks | sort -n | uniq > > /another_file_system/blocks.sorted
```

- 4. See if any of the sectors reported for the recovered file
- 5. Done

Unfortunately, lack of collisions is not enough to guarantee that a recovery is correct. Consider:

- 1. User tom creates a file F(tom) containg the details of his baseball card collection. This results in the creation of an inode I(tom) mapped into the inode space of the filesystem and a vector of blocks V(tom) containing file data or metadata.
- 2. User tom deletes F(tom). Presuming that no other links to I(tom) exist, the filesystem is now free to reclaim (seperately) both the inode entry I(tom) and the blocks listed in V(tom).
- 3. User dick creates a file F(dick) containing a great new picture of two midgets and a horse from alt.rec.stepladders.and.livestock. This results in the creation of an inode I(dick) mapped into the inode space of the filesystem and a vector of blocks V(dick) containing file data or metadata. Let us stipulate, for the example, that V(dick) exactly equals V(tom) which is to say that the picture of midgets now occupies the blocks previously dedicated to the baseball cards.
- 4. At this point, V(dick) may contain blocks reclaimed from V(tom). This does not imply that I(dick) is mapped into the filesystem on the same inode number as I(tom). We can detect this block reuse when recovering F(tom) by exhaustively comparing the elements of V(tom) against the elements of every other V() associated with every other I() in the filesystem we would learn that V(dick) contains blocks reclaimed from V(tom). Obviously, we must regard at least portions of F(tom) as unrecoverable if its blocks have been recycled!
- 5. User dick deletes F(dick). Presuming that no other links to I(dick) exist, the filesystem is now free to reclaim (seperately) both the inode entry I(dick) and the blocks listed in V(dick).
- 6. At this point, a simple validation pass (as per above) would fail to reveal that V(tom) was reused as V(dick) because F(dick) has been removed. If we had failed to consider this point (as analysts surely have) we might have already fired tom from his job J(tom) for the midget picture! Perhaps we could increase the sophistication of the validation pass to survey every V() associated with every inode in the inode space we could maybe see that a file, F(dick), was created after F(tom) and contained blocks reclaimed from V(tom).

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7. The waters muddy further when user harry creates a file F(harry) containing his Christmas shopping list. This results in the creation of an inode I(harry) mapped into the inode space of the filesystem and a vector of blocks V(harry) containing file data or metadata. Let us stipulate, for the example, that I(harry) is mapped onto the same inode number that I(dick) was mapped onto.

8. At this point, we are still tempted to believe that our recovered F(tom) contains a picture of midgets ; further that tom was deliberately hiding his pictures under a fake name. Unlike previous steps where a mechanism existed for determining that elements of V(tom) had been reallocated, every record of F(dick) – namely I(dick) and V(dick) – has been obliterated.

While that situation sounds dire, there may still be hope for tom before he's (wrongly) sent off to jail for child pornography. Modern journalling filesystems may contain extra information that allows us to exactly determine whether tom's original file is recoverable.

2.6 Library Interface

3 Credits

I would like to thank the NASA Office of Inspector General for having the special needs that caused me to write this utility in the first place.

I would like to thank Bob Hergert of the *Defense Computer Forensics Lab* for developing the xscale companion utility and for testing this product.

I would like to thank the FBI SWG-DE (Scientific Working Group on Digital Evidence) for working to establish and promulgate guidelines that make it feasable to apply high-performance computing techniques to the computer forensics process.